

CPP-A12V80A-SA-CAN

ElectroCraft CompletePower™ Plus Universal Servo Drive

More Power in a Smaller Package

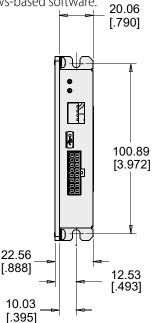
Introducing ElectroCraft's Universal Drive,

the newest addition to the ElectroCraft CompletePower™ Plus family of DC motor drives.

The Universal Drive takes performance, efficiency and flexibility to the next level, utilizing state-of-the-art digital drive technology combined with an intuitive and highly configurable user interface. Perfect for a wide range of industrial, commercial market, and consumer product applications. The CPP-A12V80A-SA-CAN is one of several standard capacities in the model lineup. Customized versions are also offered to meet large volume OEM requirements.

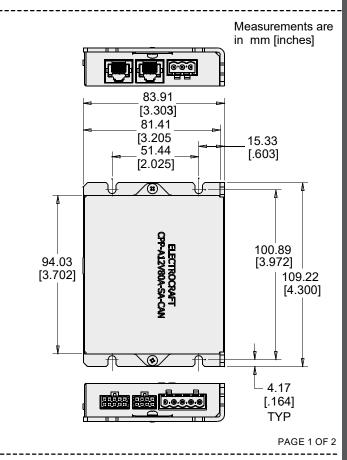
- Driven by design to be one of the most space efficient, low voltage, digital servo drives available.
- Utilizing the latest in digital drive architecture to provide software selectable control mode operation.
- Compatible with Brushless DC, Permanent Magnet Brushed DC, and Stepper Motors from 12 to 80 VDC and up to 12A continuous, 30A peak current.
- Sine-wave commutation using either hall sensor or encoder feedback provides smooth torque.
- Modes of operation include Speed, Current, and Position control
- Advanced Field Oriented Control provides high dynamic response resulting in a robust motor controller with low torque ripple that produces smoother, more efficient motion!
- Single step up to 256 micro-steps in open or closed-loop control for Stepper motors (1MHz max step rate).
- Built in USB and CAN Bus Communications up to 1Mbit/s.

• Easy setup and configuration using ElectroCraft CompleteArchitect™ Windows-based software.





CPP-A12V80A-SA-CAN Universal Servo Drive		
Output Power, Peak:	2075 Watts	
Phase Current Peak:	30 Amps (peak of sine)	
Phase Current Cont.:	12 Amps (peak of sine)	
Output:	+12 to +80 VDC	
Output Frequency:	20, 40, 80 kHz (selectable)	



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ElectroCraft CompletePower™ Plus Universal Servo Drive

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J7 - CAN In

2

3

3 Gnd

5

6 Shield

2 ID-Bit1

1 CAN-H In

Gnd

CAN-L In

Enbl / In+

Enbl/In-

Shield

GND

8 CANV+

J8 - CAN Out

CAN-H Out

CAN-L Out

Enbl / Out-

+5Vout

GND

8 CANV+

SW 1- Axis ID

1 ID-Bit0

ID-Bit2

ID-Bit3

TECHNICAL SPECIFICATIONS

Pinouts:

J1	-	Su	pр	ly

- Gnd Power
- 3 PE

J2 - Motor

- A/A+
- 2 B / A-
- 3 C/B+
- Brake / B-
- Frame

J3 - Hall

- Hall 1
- 2 Hall 2
- 3 Hall 3 Temp+
- Frame
- +5Vout
- Gnd
- 8 Temp-

J4 – Encoder

- +5Vоит
- +5Vout 2
- 3 A+
- 4 B+ 5 Z+
- 6 Frame
- 7 Gnd
- 8 A-
- 9 B-
- 10 Z-

J5 - I/O

- Frame-
- 2 A ln+Step / A In2+ 3
- Limit+
- Enable
- eBrake
- Fault
- +5Vout 8
- A Out1
- 10 A In1-Dir / A In2-11
- Limit-12
- 13 Brake
- 14 Capture
- Ready 15
- 16 Gnd

USB Communications

Indicators (LED)

Green - Ready Red - Fault

Features:

- +12 to +80 VDC power supply input.
- 12 Amps Cont., 30 Amps Peak (2 seconds).
- 2 and 4 quadrant modes.
- Sinusoidal and Trapezoidal commutation.
- 20 kHz, 40 kHz and 80 kHz of programmable PWM frequency options.
- Current, Speed and Position modes of operation.
- USB Communications.
- CAN Bus Communications.
- Drive status diagnostics.
- +/-10V Analog command input.
- +/-10V Analog output (configurable).
- Built in short circuit, over current, over temperature, and over voltage detection.

- Digital Step and Direction inputs.
- Halls only operation mode.
- Integrated electromagnetic brake control circuit.
- Encoder mode for low speed performance.
- Integrated braking circuit control.
- +/- Travel limit inputs.
- Configurable ramp for current and
- 97% efficiency at full load.
- Selectable software protection options.
- Windows®-based setup and tuning utility software included.
- Hardware CAN Axis ID selection switches.
- Open and Closed loop stepper control

Model Specifications:

DC Input	VDC+12 to +80
Output	VDC+12 to +80
Output Power, Peak	Watts 2075
Phase Cur. Peak	Amps 30 (peak of sine)
Phase Cur. Cont.	Amps 12 (peak of sine)
Output Frequency	kHz
Motor Inductance	mH 0.1 to 50
Motor feedback &	VDC+5, 5% reg.
Interface power	mA 250 max.
Ambient Temp. Range	°C 0 to 40
Humidity	5% to 95% RH, Non-Condensing
Control Loops	
Speed loop update rate	Digitally adjustable up to 10 kHz
Current loop update rate	20 kHz
Position loop update rate	Digitally adjustable up to 10 kHz
Loop operation	Velocity, Torque, Position
Feedback	
Halls sensors	120°
Encoder	4 MHz, Differential or Single-ended
Current resolution	12 bit
Speed resolution	
Position resolution	
Motors	
IVIU(UIS	BLDC / PMDC / Stepper

CPP Model Number:

CPP - A















Continuous Current

Voltage Revision

Form Factor SA = Stand Alone

Your Genius. Our Drive.

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